

G2 - Metodi Algebrici - Reduam

Titolo nota

09/09/2010

1. Coord. cartesiane (sta. di calcolo)
 2. Complessi (geometria della cps e del trw)
 3. Vettori (comb. lineari convesse)
prodotti vettoriali
- [Coord. baricentriche]

Coniche: $p(x,y) = \underline{ax^2} + \underline{2bxy} + cy^2 + \underline{2dx} + 2ey + f$

- $x^2 + y^2 - 1 = 0$
 - $x^2 - y^2 - 1 = 0$
 - $x^2 - y = 0$
- $(x^2 + y^2 + 1 = 0 \text{ È FINITA})$

$a > 0$

$$\left(\sqrt{a} \cdot x + \frac{b}{\sqrt{a}} y + \frac{d}{\sqrt{a}}\right)^2 = ax^2 + \frac{b^2}{a} y^2 + \frac{d^2}{a} + 2bxy + 2dx + 2 \frac{bd}{a} y$$

$$cy^2 \left(c - \frac{b^2}{a}\right) + 2y \left(e - \frac{bd}{a}\right) + f - \frac{d^2}{a} =$$

$$= \boxed{+} + k$$

$c - \frac{b^2}{a} \geq 0$
 $ac - b^2 \geq 0$

$\alpha t^2 + \beta t + \gamma = \boxed{+} \pm h^2$

$+ =$ max 2 radici
 $- =$ 2 radici

$h=0$ 1 radice

$a^2 - b^2 = 0$ OK

$a(x)^2 + b(x)^2 = 0$
 $a(x) = b(x) = 0$

$$\begin{array}{ll} x^2+1 & \Delta < 0 \\ x^2-1 & \Delta > 0 \\ x^2 & \Delta = 0 \end{array}$$

$$p(x,y) = ax^2 + 2bxy + cy^2 + \dots$$

$$\Delta < 0$$

ellisse

$$\Delta = 0$$

parabola

$$\Delta > 0$$

iperbole

Cartesiana:

$$\boxed{\text{RETTA}} \\ ax + by + c = 0$$

Parametrica:

$$\begin{cases} x = pt + q \\ y = rt + s \end{cases} \quad t \in \mathbb{R}$$

$$\boxed{\text{CIRCONFERENZA}}$$

$$\begin{cases} x = \cos \theta \\ y = \sin \theta \end{cases}$$

$$\begin{cases} x = \frac{1-t^2}{1+t^2} \\ y = \frac{2t}{1+t^2} \end{cases}$$

$$t = \tan \frac{\theta}{2}$$

$$\cos^2 \frac{\theta}{2} =$$

$$x = \tan \alpha$$

$$x^2 = \frac{\sin^2 \alpha}{\cos^2 \alpha}$$

$$\cos^2 \alpha = \frac{1}{x^2+1}$$

$$x^2+1 = \frac{\cos^2 \alpha + \sin^2 \alpha}{\cos^2 \alpha} = \frac{1}{\cos^2 \alpha}$$

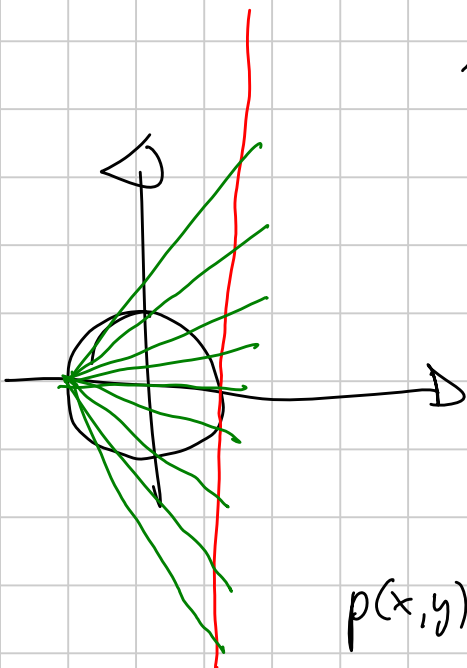
$$\cos 2\alpha = 2\cos^2 \alpha - 1 = \frac{2}{x^2+1} - 1 = \frac{2-x^2-1}{x^2+1} = \frac{1-x^2}{1+x^2}$$

$$t = \frac{m}{n} \quad m, n \in \mathbb{Z}$$

$$x = \frac{1 - \frac{m^2}{n^2}}{1 + \frac{m^2}{n^2}}$$

$$(n^2 - m^2, 2mn, n^2 + m^2)$$

$$y = \frac{\frac{2mn}{n}}{1 + \frac{m^2}{n^2}}$$



fascio di rette : $y = m(x+1)$

$$\begin{cases} y = m(x+1) \\ x^2 + y^2 - 1 = 0 \end{cases}$$

$p(x,y)$ = grado 2 $a(x)$ = lineare (1° grado)

$p(x, a(x))$ = grado 2

$p(x,y)=0$ Conica $(x_0, y_0) \in \text{Conica}$

$$\begin{cases} y - y_0 = m(x - x_0) \\ p(x,y) = 0. \end{cases}$$

Se $p(x,y) \in \mathbb{Q}[x,y]$ ($\mathbb{Q} \subseteq \mathbb{Z}$), $x_0, y_0 \in \mathbb{Q} \text{ o } \mathbb{Z}$

$m \in \mathbb{Q}, \mathbb{Z} \Rightarrow$ altro punto $\in \mathbb{Q}, \mathbb{Z}$

$$\frac{y_0 - y_1}{x_0 - x_1} \in \mathbb{Q} (\mathbb{Z})$$

\uparrow
 $\mathbb{Q} (\text{o } \mathbb{Z})$

$$\begin{cases} x = \frac{r_1(t)}{r_2(t)} \\ y = \frac{s_1(t)}{s_2(t)} \end{cases} \quad r_i, s_i \in \mathbb{Z}(t)$$

3° grado = 3 soluzioni

non dividibile ($\cancel{\mathbb{Z}} \text{ o } \mathbb{Q}$)
 $q(x) \in \mathbb{Q}[x]$

$p(x) \in \mathbb{Q}[x]$
indivisibile su $\mathbb{Q}[x]$
ha radici $\zeta_1, \zeta_2, \zeta_3$

t.c. $q(\zeta_1) = 0 \quad q(\zeta_2) \neq 0.$

Il metodo delle corde funziona se:

1) il 3° grado è finito ($(x+iy)(x^2+y^2-1)=0$)

2) la curva $p(x,y)=0$ è fatta così:



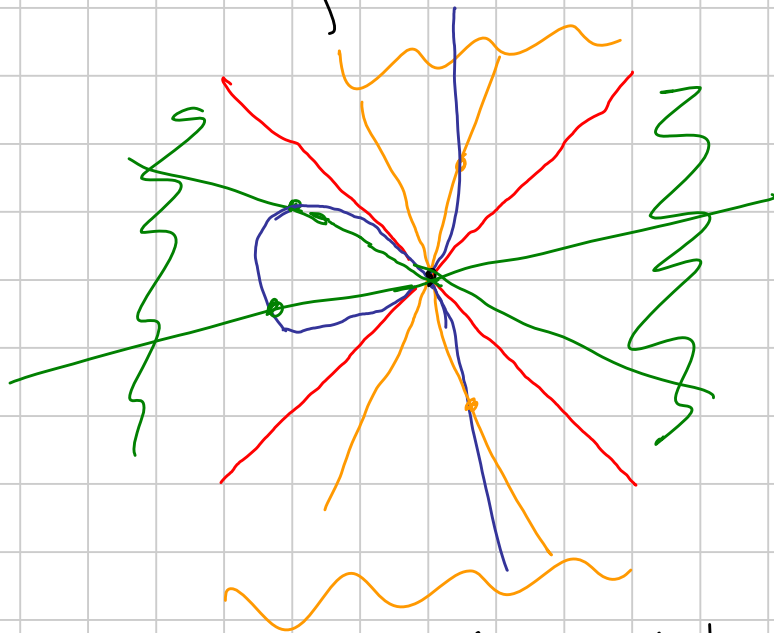
$$p(x,y) = 0$$

← (90°)

$$p(x,y) = 0$$

$$\parallel$$

$$x^2 - y^2 + y^3$$



→ NOBO
(mode)

$$\parallel$$

$$\begin{cases} p(x,y) = 0 \\ \frac{dp}{dx} = 0 \\ \frac{dp}{dy} = 0 \end{cases}$$

$$\frac{d \cdot x^n}{dx} = n \cdot x^{n-1}$$

$$\frac{d y^n}{dx} = 0$$

$$\frac{d y^n}{dy} = n y^{n-1}$$

$$\frac{d y^n}{dx} = 0$$

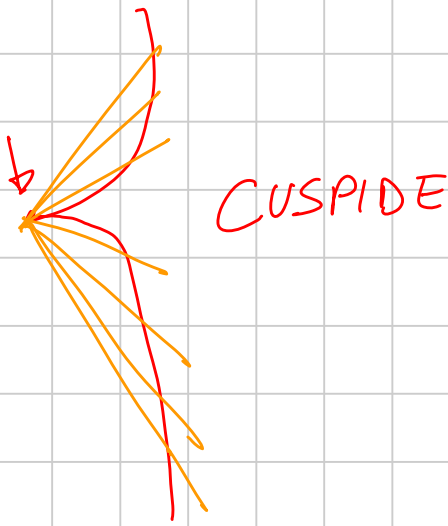
$$\frac{d a \cdot f(x,y)}{d \Omega} = a \cdot \frac{d f(x,y)}{d \Omega}$$

$$\frac{d f(x,y) \cdot g(x,y)}{d \Omega} = \frac{df}{d \Omega} \cdot g + f \cdot \frac{dg}{d \Omega}$$

$$\frac{d p(x,y)}{dx} = \frac{d x^2 - y^2 + y^3}{dx} = 2x$$

$$\frac{dp}{dy} = -2y + 3y^2$$

$$x^2 = y^3$$



ES: $x^2 + y^2 = 2z^2$

— * —

Determinante:

$$\begin{cases} ax + by = 0 \\ cx + dy = 0 \end{cases}$$

esiste sol $\neq (0,0) \iff a = \lambda c$

$$b = \lambda d$$

$$\frac{a}{c} = \frac{b}{d}$$

$$\iff ad - bc = 0$$

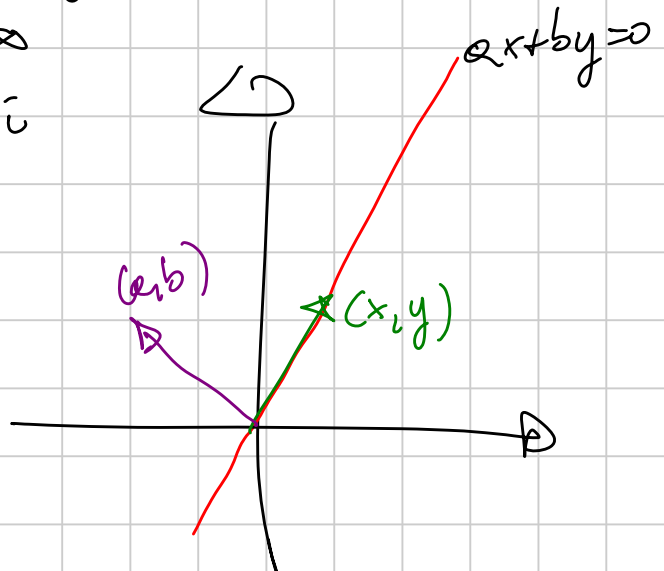
determinante
del sistema

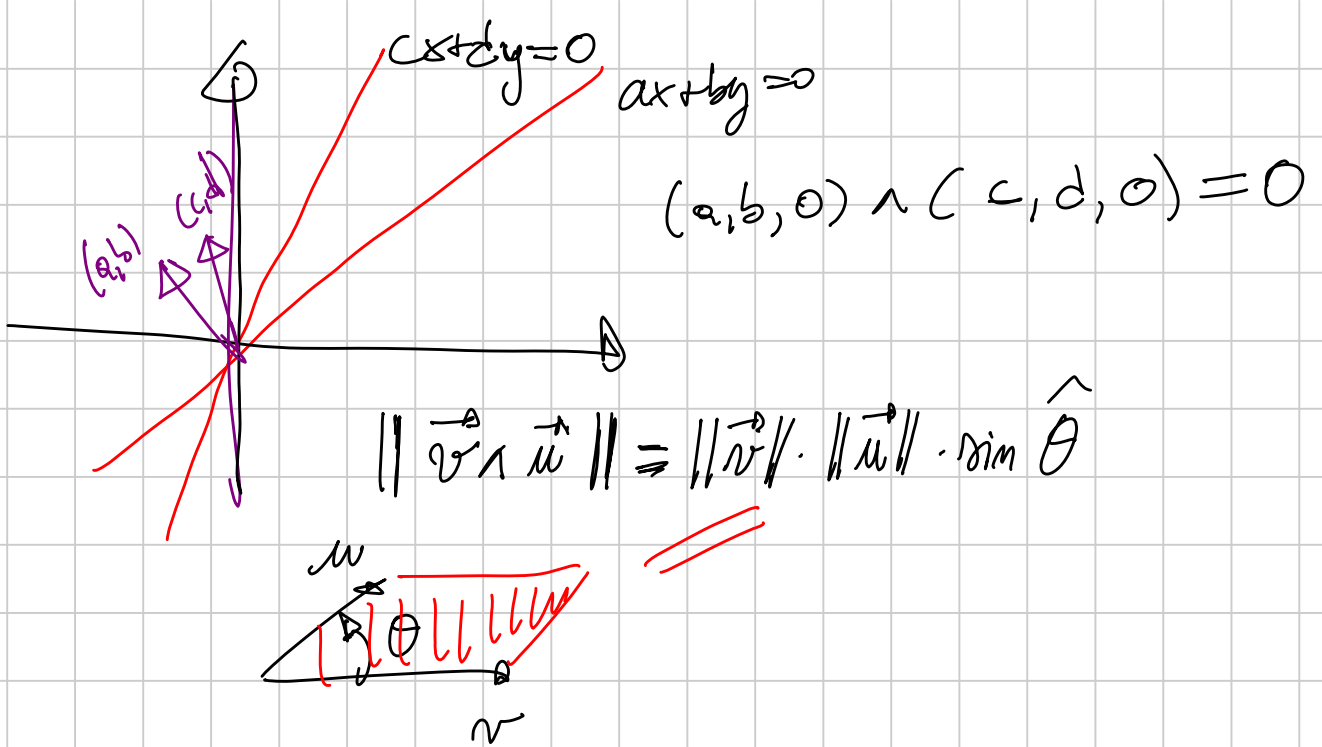
$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc$$

$$0 = ax + by = \langle (a, b), (x, y) \rangle$$

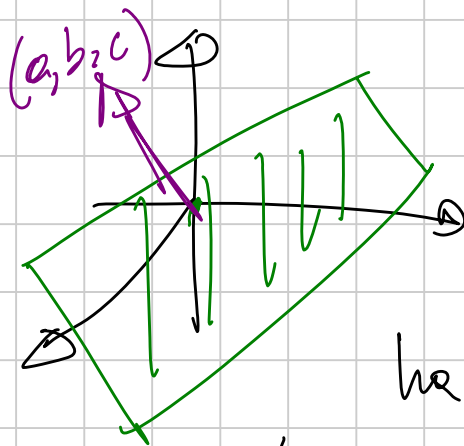
vettori

$\iff (a, b)$
perp. a
 (x, y)





Im 3d: $(a,b,c) \cdot (x,y,z) = 0$



$$\text{Se } \begin{cases} ax+by+cz=0 \\ dx+ey+fz=0 \\ gx+hy+jz=0 \end{cases}$$

he altre $\neq (0,0,0)$

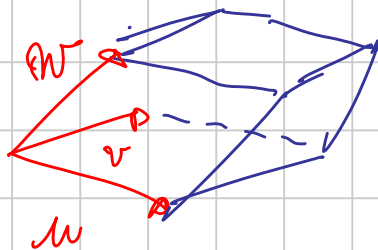
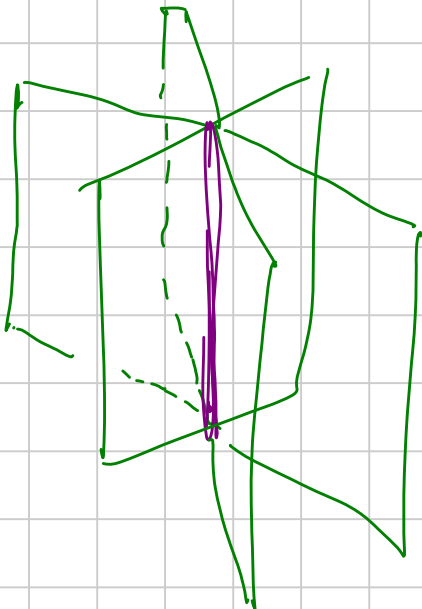
c'è una \vec{w} in comune
(v)

$(a,b,c), (d,e,f), (g,h,j)$

sono \perp a v



$$\text{Vol} = 0$$



base $= \vec{u} \wedge \vec{v}$

$$\pm \text{Vol} = (\vec{u} \wedge \vec{v}) \cdot \vec{w}$$

C^1_v una sol' linea nulla $\iff [(a,b,c) \wedge (d,e,f)] \cdot (g,h,j)$

$$(a,b,c) \wedge (d,e,f) = (bf-ec, dc-af, ae-bd)$$

$$\pm \text{Vol} = (gbf + hdc + jae - gec - hef - jbd)$$

$$\det \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & j \end{pmatrix}$$

$$\det \begin{pmatrix} \vec{v} \\ \vec{u} \\ \lambda \vec{v} + \mu \vec{u} \end{pmatrix} = 0$$

$$\begin{cases} ax+by=c \\ dx+ey=f \end{cases}$$

$$D = \det \begin{vmatrix} a & b \\ d & e \end{vmatrix}$$

$$D_x = \det \begin{vmatrix} c & b \\ f & e \end{vmatrix}$$

$$x = \frac{D_x}{D}$$

$$y = \frac{D_y}{D}$$

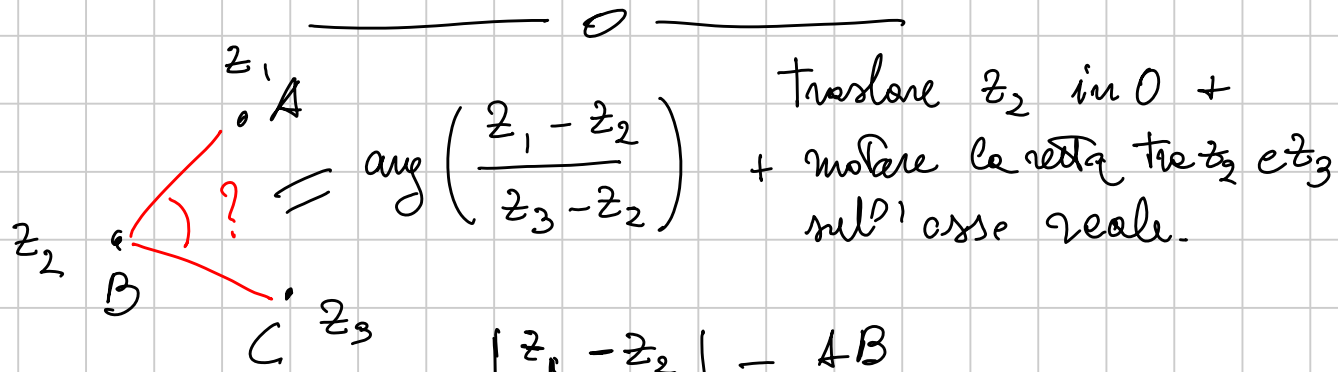
$$D_y = \det \begin{vmatrix} a & c \\ d & f \end{vmatrix}$$

Oss: $\begin{cases} ax+by+cz=0 \leftarrow \text{piano } \perp (a,b,c) \\ dx+ey+fz=0 \leftarrow \text{piano } \perp (d,e,f) \end{cases}$

la retta che risolve il sistema è

$$\lambda \cdot (a,b,c) \wedge (d,e,f) \quad \lambda \in \mathbb{R}$$

$$\lambda \cdot (bf-ec, dc-af, ae-bd)$$



Traslare z_2 in 0 +
 + muovere la retta tra z_2 e z_3
 sull'asse reale.

$$\left| \frac{z_1 - z_2}{z_3 - z_2} \right| = \frac{AB}{BC}$$

dirett.

$$\frac{w_1 - w_2}{w_3 - w_2} = \frac{z_1 - z_2}{z_3 - z_2}$$

\longleftrightarrow i Δ sono simili

(con i coniugati: inv. simile)



$$\det \begin{pmatrix} z_3 - z_2 & z_1 - z_2 \\ w_3 - w_2 & w_1 - w_2 \end{pmatrix} = 0$$



$$\det \begin{pmatrix} 1 & 1 & 1 \\ z_1 & z_2 & z_3 \\ w_1 & w_2 & w_3 \end{pmatrix} = 0$$

Δ equilatero $\longleftrightarrow \begin{vmatrix} 1 & 1 & 1 \\ z_1 & z_2 & z_3 \\ \zeta_3 & \zeta_3^2 & 1 \end{vmatrix} = 0$



$\zeta_3 = \text{rad. } 3^{\text{a}} \text{ di } 1 \quad \zeta_3^2 = \overline{\zeta_3}$

$$z_1 + \zeta_3 z_2 + \zeta_3^2 z_3 = 0$$

Δ equilatero $\longleftrightarrow ABC \cong BCA$

($ABC \cong BAC$ non è)