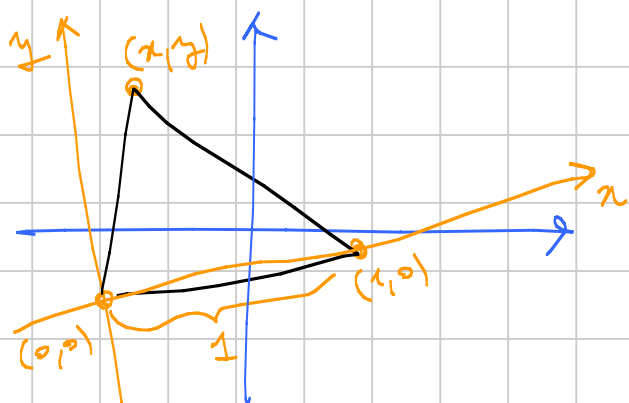


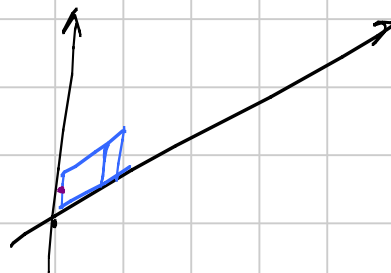
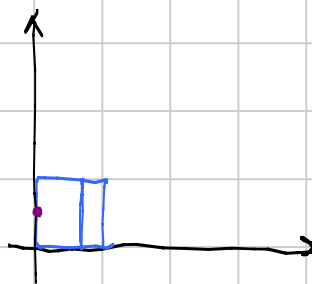
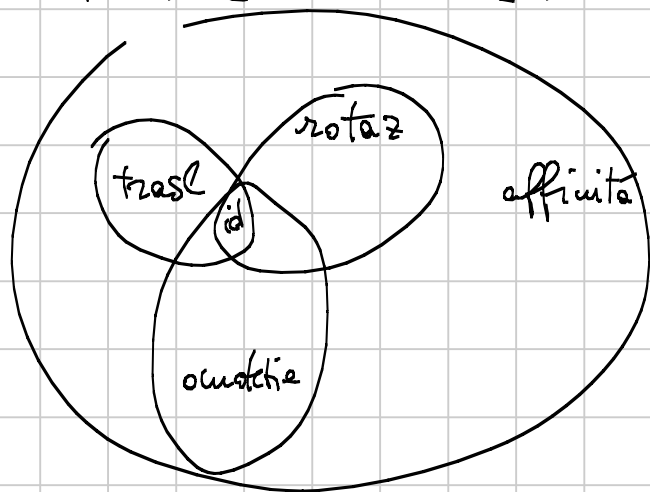
Metodi algebrici : coordinate cartesiane
 vettori
 complessi

☐ CARTESIANE



problemi invarianti per
rotazioni e traslazioni
 ↳ scegli O e la
 direzione di x in
 modo comodo
 se non è fissata una scala,
 fisso anche quelle
 (inv. per omotetie)

☐ AFFINITÀ e INVARIANZA



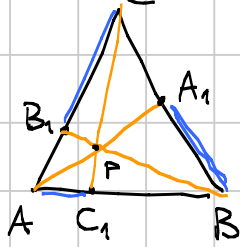
$$\begin{cases} x' = ax + by + c \\ y' = dx + ey + f \end{cases}$$

a, b, c, d, e, f determinano l'affinità

$$P' = MP + Q \quad M = \begin{pmatrix} a & b \\ d & e \end{pmatrix} \quad Q = \begin{pmatrix} c \\ f \end{pmatrix}$$

Conservano : parallelismo tra rette (manda rette in rette)
 rapporti tra aree
 rapporti tra segmenti paralleli

Es 1. Teorema di Ceva

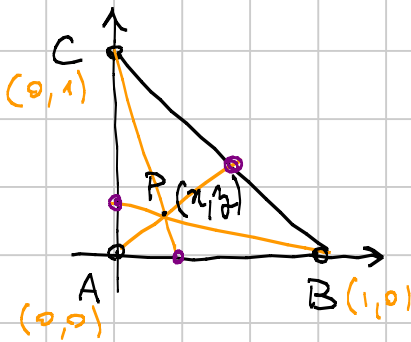


$$AC_1 \cdot BA_1 \cdot CB_1 = C_1B \cdot A_1C \cdot B_1A$$

$$\frac{AC_1}{C_1B} \cdot \frac{BA_1}{A_1C} \cdot \frac{CB_1}{B_1A} = 1$$

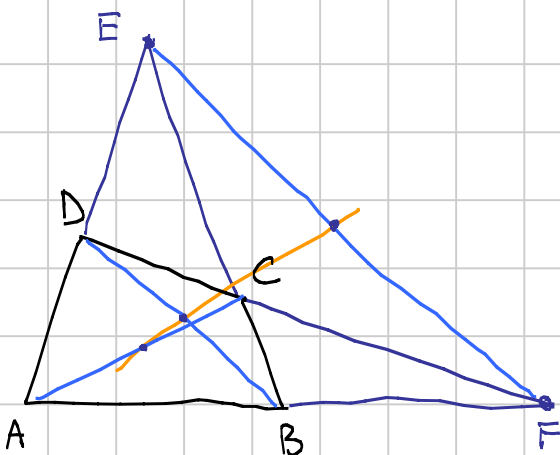
↑ rapporto tra segmenti paralleli

enunciato invariante per affinità

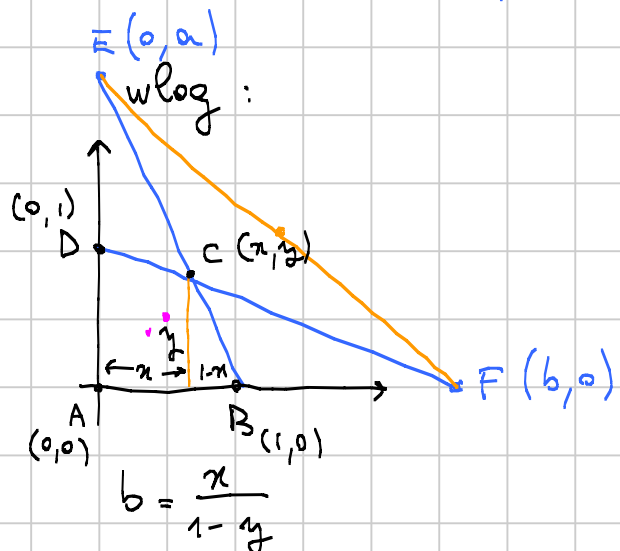


posso mandare 3 punti qualsiasi
 in 3 punti qualsiasi
 (a meno che non siano allineati)

Es 2. Quadrilatero A, B, C, D $E = AD \cap BC$ $F = AB \cap CD$
 Tesi : i pts medi di EF, AC, BD sono allineati



enunciato invariante per affinità



$$a : y = 1 : 1 - x \quad a = \frac{y}{1-x}$$

$$b = \frac{x}{1-y}$$

$$\text{pto medio di EF} : \left(\frac{b}{2}, \frac{a}{2} \right) = \left(\frac{x/2}{1-y}, \frac{y/2}{1-x} \right)$$

$$\text{pto medio di AC} : \left(\frac{x}{2}, \frac{y}{2} \right) \quad Q$$

$$\text{pto medio di BD} : \left(\frac{1}{2}, \frac{1}{2} \right) \quad P$$

Per vedere se tre punti P, Q, R sono allineati, verifico se esiste $\lambda \in \mathbb{R}$ t.c. $\lambda P + (1-\lambda)Q = R$

$$\begin{cases} \lambda x_P + (1-\lambda)x_Q = x_R \\ \lambda y_P + (1-\lambda)y_Q = y_R \end{cases}$$

$$\begin{cases} \lambda + (1-\lambda)x = \frac{x}{1-y} \\ \lambda + (1-\lambda)y = \frac{y}{1-x} \end{cases}$$

$$\begin{cases} \lambda(1-x) + x = \frac{x}{1-y} \\ \lambda(1-y) + y = \frac{y}{1-x} \end{cases}$$

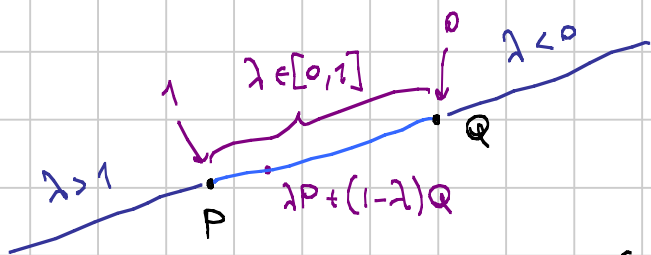
$$\begin{cases} \lambda = \left(\frac{x}{1-y} - x \right) \frac{1}{1-x} = \frac{x y}{(1-x)(1-y)} \\ \lambda = \frac{x y}{(1-x)(1-y)} \end{cases}$$

Un po' di teoria

$y = mx + q$ retta non verticale
 $ax + by + c = 0$ retta qualunque



Punti del segmento: combinazioni lineari convesse degli estremi
 $(\lambda x_0 + (1-\lambda)x_1; \lambda y_0 + (1-\lambda)y_1)$
 $0 \leq \lambda \leq 1, \lambda + (1-\lambda) = 1$



$$\begin{cases} \lambda x_P + (1-\lambda)x_Q = x & \text{retta per PQ} \\ \lambda y_P + (1-\lambda)y_Q = y \end{cases}$$

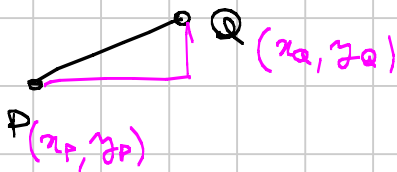
$$\begin{cases} x = \lambda(x_P - x_Q) + x_Q \\ y = \lambda(y_P - y_Q) + y_Q \end{cases} \quad \text{eq. parametrica}$$

$$\lambda = \frac{x - x_Q}{x_P - x_Q}$$

$$y = \frac{y_P - y_Q}{x_P - x_Q} (x - x_Q) + y_Q \quad \text{eq. implicite}$$

DISTANZA e CIRCONFERENZA

$$d(P, Q) = \overline{PQ} = \sqrt{(x_P - x_Q)^2 + (y_P - y_Q)^2} \quad \text{distanza Euclidea}$$



$$\Gamma = \left\{ (x, y) : d((x, y), (x_0, y_0)) = r \right\}$$

$$(x - x_0)^2 + (y - y_0)^2 = r^2$$

$$x^2 + y^2 - 2x_0x - 2y_0y + \underbrace{x_0^2 + y_0^2 - r^2}_c = 0$$

$$x^2 + y^2 + ax + by + c = 0$$

non sempre questa è una circonferenza.

$$x_0 = -\frac{a}{2} \quad y_0 = -\frac{b}{2} \quad \frac{a^2}{4} + \frac{b^2}{4} - c \stackrel{?}{\leq} 0$$

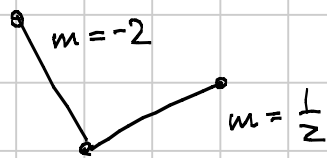
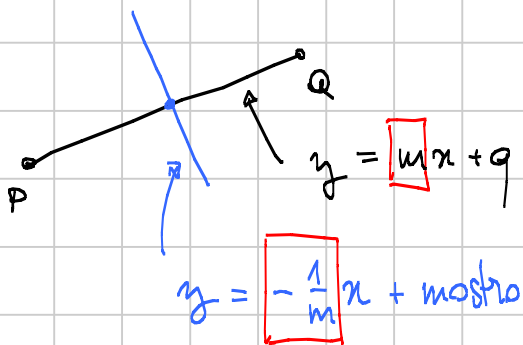
Asse di un segmento

$$\alpha = \left\{ (x, y) : d((x, y), (x_P, y_P)) = d((x, y), (x_Q, y_Q)) \right\}$$

$$(x - x_Q)^2 + (y - y_Q)^2 = (x - x_P)^2 + (y - y_P)^2$$

$$2x(x_p - x_q) + 2y(y_p - y_q) + x_q^2 + y_q^2 - x_p^2 - y_p^2 = 0$$

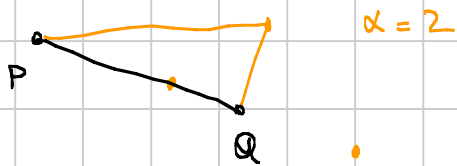
$$ax + by + c = 0$$



equazione retta ortogonale

● Circonferenza di Apollonio

$$r = \left\{ (x, y) : d((x, y), (x_p, y_p)) = \alpha \cdot d((x, y), (x_q, y_q)) \right\} \quad \begin{matrix} \alpha \neq 1 \\ \alpha > 0 \end{matrix}$$



$$(x - x_q)^2 + (y - y_q)^2 = \alpha^2 (x - x_p)^2 + \alpha^2 (y - y_p)^2$$

$$(1 - \alpha^2)x^2 + (1 - \alpha^2)y^2 + \dots = 0 \quad \text{circonferenza}$$

● Bisettrici, potenza, asse radicale ... alle fine, x riesco

▣ VETTORI

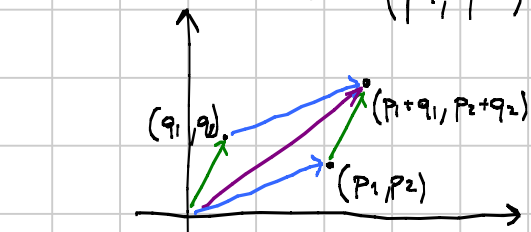
$$\vec{X} = (x_1, x_2, x_3, \dots, x_n) \quad n = 2, 3 \text{ o piú} \quad x_i \in \mathbb{R} \quad i = 1, 2, \dots, n$$

$$\vec{X}, x, \alpha \quad \vec{Y} = (y_1, y_2, \dots, y_n)$$

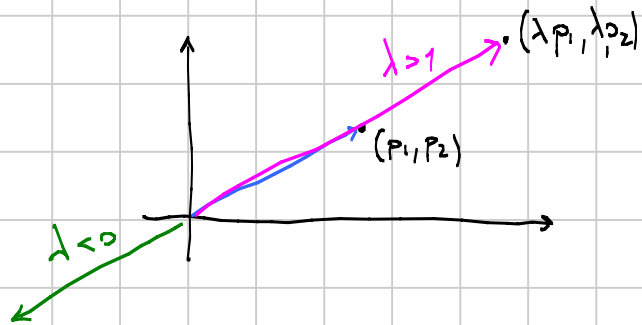
$$\vec{X} + \vec{Y} = (x_1 + y_1, x_2 + y_2, \dots, x_n + y_n) \quad \text{somma}$$

$$\lambda \in \mathbb{R} \quad \lambda \vec{X} = (\lambda x_1, \lambda x_2, \dots, \lambda x_n) \quad \text{prod per scalare}$$

$$n=2 \quad \vec{P} = (p_1, p_2) \quad \vec{Q} = (q_1, q_2) \quad \vec{P} + \vec{Q} = (p_1 + q_1, p_2 + q_2)$$



\vec{P} è il punto o la freccia
a seconda di cosa ci fa comodo



• Prodotto scalare

$$\mathbb{R} \ni \vec{X} \cdot \vec{Y} = \langle \vec{X}, \vec{Y} \rangle = (\vec{X}, \vec{Y}) = x_1 y_1 + x_2 y_2 + \dots + x_n y_n = \sum_{i=1}^n x_i y_i$$

simmetrico

$$0 \leq \vec{X} \cdot \vec{X} = \sum_{i=1}^n x_i^2 =: \|\vec{X}\|^2 \quad \text{norma (o lunghezza) del vettore al quadrato}$$

$$(\lambda \vec{X}) \cdot \vec{Y} = (\lambda x_1, \dots) \cdot (y_1, \dots) = \lambda x_1 y_1 + \lambda x_2 y_2 + \dots = \lambda (\vec{X} \cdot \vec{Y}) = \vec{X} \cdot \lambda \vec{Y}$$

$$(\vec{X} + \vec{Y}) \cdot \vec{Z} = \dots = \vec{X} \cdot \vec{Z} + \vec{Y} \cdot \vec{Z} \quad \text{distributiva}$$

$$0 \leq \|\vec{X} + \lambda \vec{Y}\|^2 = (\vec{X} + \lambda \vec{Y}) \cdot (\vec{X} + \lambda \vec{Y}) = \vec{X} \cdot (\vec{X} + \lambda \vec{Y}) + \lambda \vec{Y} \cdot (\vec{X} + \lambda \vec{Y})$$

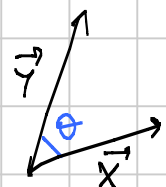
$$= \vec{X} \cdot \vec{X} + \lambda \vec{X} \cdot \vec{Y} + \lambda \vec{Y} \cdot \vec{X} + \lambda^2 \vec{Y} \cdot \vec{Y} = \|\vec{X}\|^2 + 2(\vec{X} \cdot \vec{Y})\lambda + \|\vec{Y}\|^2 \lambda^2$$



$$\frac{\Delta}{4} = (\vec{X} \cdot \vec{Y})^2 - \|\vec{X}\|^2 \|\vec{Y}\|^2 \leq 0$$

$$|\vec{X} \cdot \vec{Y}| \leq \|\vec{X}\| \|\vec{Y}\| \quad \text{C-S}$$

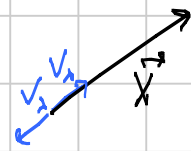
$$n=2 \quad \vec{X} \cdot \vec{Y} := x_1 y_1 + x_2 y_2 \stackrel{\text{thm}}{=} \|\vec{X}\| \|\vec{Y}\| \cos \theta$$



in C-S vale = se e solo se $\vec{X} \parallel \vec{Y} \quad \vec{X} = \nu \vec{Y} \quad \nu \in \mathbb{R}$

$$\frac{\vec{X} \cdot \vec{Y}}{\|\vec{X}\| \|\vec{Y}\|} = \cos \theta$$

lo dimostro



$$\begin{aligned} \frac{\vec{X} \cdot \vec{Y}}{\|\vec{X}\| \|\vec{Y}\|} &= \frac{\vec{X}}{\|\vec{X}\|} \cdot \frac{\vec{Y}}{\|\vec{Y}\|} = (\cos \alpha, \sin \alpha) \cdot (\cos \beta, \sin \beta) = \cos \alpha \cos \beta + \sin \alpha \sin \beta \\ &= \cos(\alpha - \beta) = \cos(\beta - \alpha) = \cos \theta \end{aligned}$$

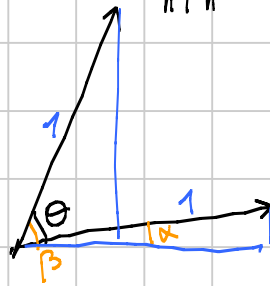
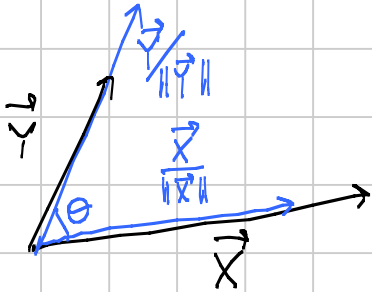
$$\vec{V}_\lambda := \lambda \vec{X} \quad \|\vec{V}_\lambda\| = \|\lambda \vec{X}\| = \sqrt{\|\lambda \vec{X}\|^2} = \sqrt{\lambda \vec{X} \cdot \lambda \vec{X}} = |\lambda| \sqrt{\vec{X} \cdot \vec{X}} = |\lambda| \|\vec{X}\|$$

$$\|\lambda \vec{X}\| = |\lambda| \|\vec{X}\|$$

$$\|\vec{V}_\lambda\| = |\lambda| \|\vec{X}\|$$

$$\lambda = \pm \|\vec{X}\|^{-1}$$

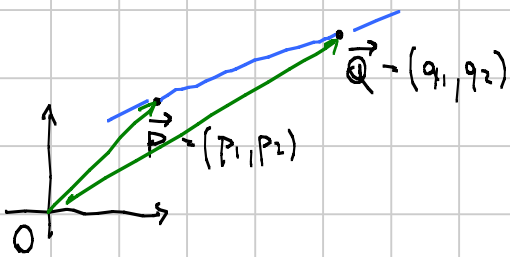
$$\frac{\vec{Y}}{\|\vec{Y}\|} = (\cos \beta, \sin \beta)$$



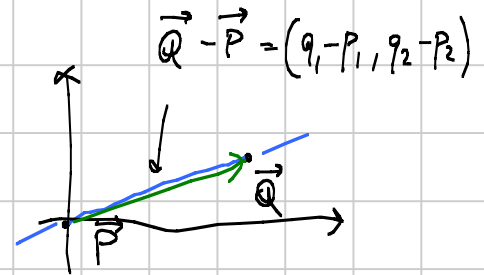
$$\frac{\vec{X}}{\|\vec{X}\|} = (\cos \alpha, \sin \alpha)$$

$$\theta = \beta - \alpha$$

• Retta per due punti



traslo \vec{P}
nell'origine
(sottraggio \vec{P})



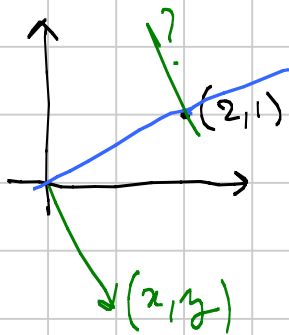
$\lambda \in \mathbb{R}$ $\lambda(\vec{Q} - \vec{P})$ sono i
punti della retta

$$\lambda(\vec{Q} - \vec{P}) + \vec{P}$$

$$\lambda \vec{Q} + (1 - \lambda) \vec{P}$$

di nuove combinazioni convessa di \vec{P} e \vec{Q}

• Retta ortogonale



la direzione verde deve essere ortogonale a quella blu

$$0 = (2,1) \cdot (x,y) = 2x + y \quad \text{ad es } x=1, y=-2$$

$(1, -2)$ è ortogonale a $(2,1)$

retta cercata: $(2,1) + \lambda(1,-2) = (2+\lambda, 1-2\lambda)$

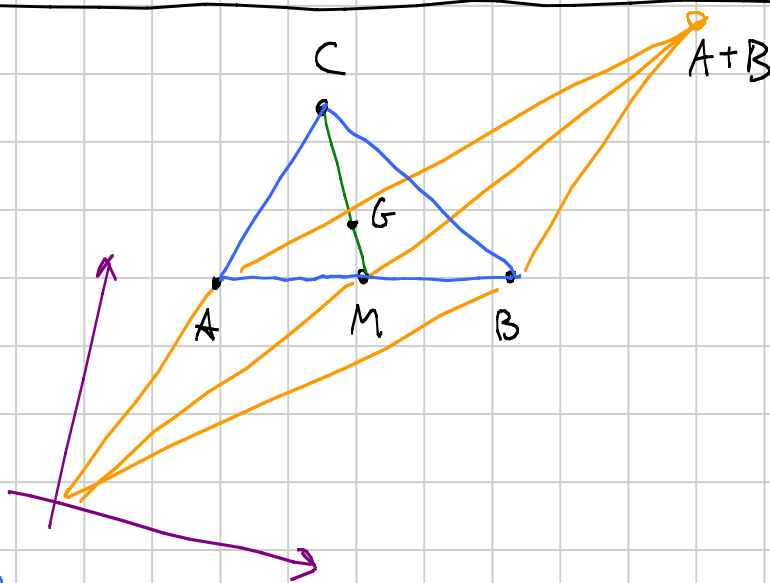
Punti dei triangoli

Baricentro

$$\vec{M} = \frac{\vec{A} + \vec{B}}{2}$$

comb. lin. conv.

\Rightarrow non dipende da O



$$\vec{G} = \frac{2}{3}\vec{M} + \frac{1}{3}\vec{C} = \frac{2}{3}\left(\frac{\vec{A} + \vec{B}}{2}\right) + \frac{1}{3}\vec{C} = \frac{\vec{A} + \vec{B} + \vec{C}}{3}$$

baricentro delle
fisica

$$\vec{G} = \frac{\vec{A} + \vec{B} + \vec{C}}{3}$$

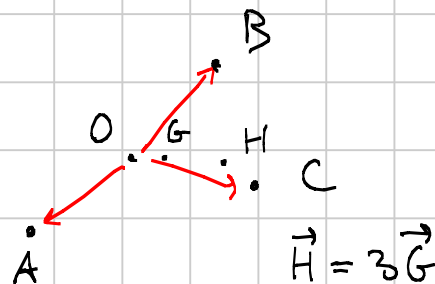
Circocentro / ortocentro

spesso ci si mette l'origine

$$\|\vec{A}\| = \|\vec{B}\| = \|\vec{C}\|$$

$$\vec{H} = \vec{A} + \vec{B} + \vec{C}$$

solo se O è l'origine



Più in generale

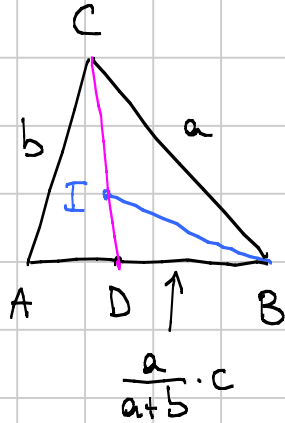
$$\vec{H} = \vec{A} + \vec{B} + \vec{C} - 2\vec{O}$$

$$\vec{H} = \vec{O} + \underbrace{(\vec{H} - \vec{O})}_{\vec{OH}} = \vec{O} + 3(\vec{G} - \vec{O}) = \vec{O} + \vec{A} + \vec{B} + \vec{C} - 3\vec{O}$$

• Incentro

$$\vec{I} = \frac{a\vec{A} + b\vec{B} + c\vec{C}}{a+b+c}$$

non dipende da 0



$$\vec{D} = \lambda\vec{A} + (1-\lambda)\vec{B}$$

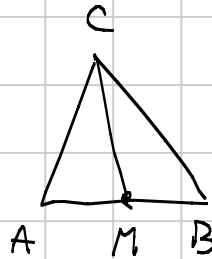
$$AD:DB = AC:CB = b:a$$

$$\vec{D} = \frac{a}{a+b}\vec{A} + \frac{b}{a+b}\vec{B}$$

$$\vec{I} = \frac{\frac{ac}{a+b}}{\frac{ac}{a+b} + a}\vec{C} + \frac{a}{\frac{ac}{a+b} + a}\vec{D}$$

$$\vec{I} = \frac{ac}{ac+a^2+ab}\vec{C} + \frac{a+b}{a+b+c} \cdot \frac{1}{a+b} (a\vec{A} + b\vec{B}) = \frac{a\vec{A} + b\vec{B} + c\vec{C}}{a+b+c}$$

• Lunghezza mediana



$$\overline{CM} = \frac{1}{2}\sqrt{2a^2 + 2b^2 - c^2}$$

$$\vec{M} = \frac{\vec{A} + \vec{B}}{2} \quad \overline{CM} = \|\vec{C} - \vec{M}\| = \left\| \frac{2\vec{C} - \vec{A} - \vec{B}}{2} \right\|$$

$$\overline{CM}^2 = \frac{1}{4} (2\vec{C} - \vec{A} - \vec{B}) \cdot (2\vec{C} - \vec{A} - \vec{B})$$

$$= \frac{1}{4} (4\|\vec{C}\|^2 + \|\vec{A}\|^2 + \|\vec{B}\|^2 + 2\vec{A} \cdot \vec{B} - 4\vec{A} \cdot \vec{C} - 4\vec{B} \cdot \vec{C})$$

$$a^2 = \overline{BC}^2 = \|\vec{B} - \vec{C}\|^2 = \|\vec{B}\|^2 + \|\vec{C}\|^2 - 2\vec{B} \cdot \vec{C}$$

$$b^2 = \|\vec{A}\|^2 + \|\vec{C}\|^2 - 2\vec{A} \cdot \vec{C}$$

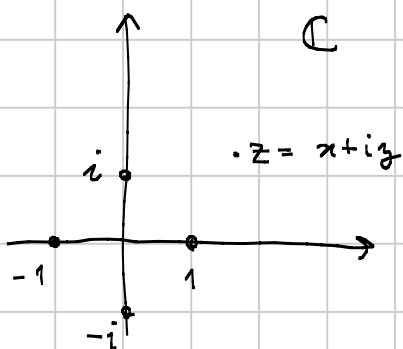
$$c^2 = \|\vec{A}\|^2 + \|\vec{B}\|^2 - 2\vec{A} \cdot \vec{B}$$

$$2a^2 + 2b^2 - c^2 = \|\vec{A}\|^2 + \|\vec{B}\|^2 + 4\|\vec{C}\|^2 + 2\vec{A} \cdot \vec{B} - 4\vec{B} \cdot \vec{C} - 4\vec{A} \cdot \vec{C}$$

$$\overline{CM}^2 = \frac{1}{4} (2a^2 + 2b^2 - c^2)$$

• altri esempi ... alle fine se riesco

COMPLESSI



come i vettori, ma in più:

- coniugio (simmetrie vs rette)
- prodotto (rotazioni)

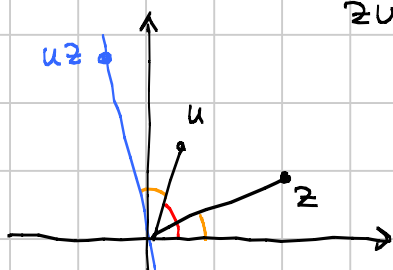
regola del parallelogramma vale sempre

$$z = x + iy$$

$$zu \in \mathbb{C}$$

$$u = r + it \in \mathbb{C}$$

$$zu = (x + iy)(r + it) = xr - yt + i(yr + xt)$$



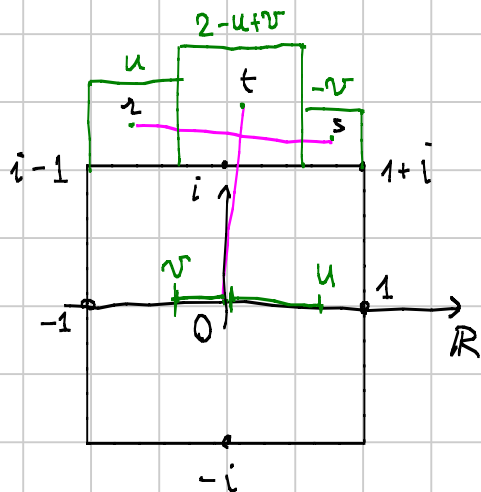
$$|z| = \sqrt{x^2 + y^2} = z\bar{z}$$

$$|zu| = |z||u|$$

$$\arg(zu) = \arg z + \arg u$$

se $|u| = 1$ moltiplicare per u esegue una rotazione
 moltiplicare per $i \rightarrow$ di 90°

Es 1



$$u, v \in \mathbb{R} \quad u \in (0, 1) \quad v \in (-1, 0)$$

$$r = i - 1 + \frac{u}{2} + i\frac{u}{2} = -1 + \frac{u}{2} + i\left(1 + \frac{u}{2}\right)$$

$$s = 1 + i + \frac{v}{2} - i\frac{v}{2} = 1 + \frac{v}{2} + i\left(1 - \frac{v}{2}\right)$$

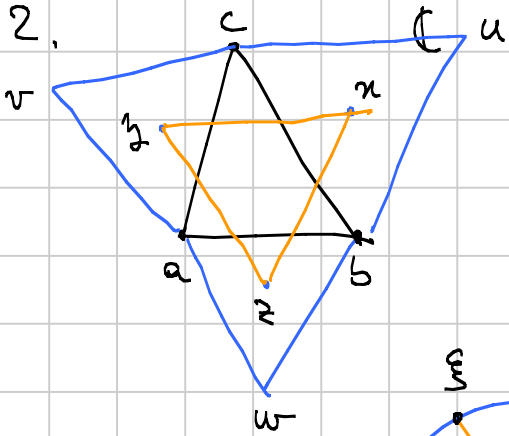
$$t = i - 1 + u + 1 - \frac{u}{2} + \frac{v}{2} + i\left(1 - \frac{u}{2} + \frac{v}{2}\right)$$

$$= \frac{u+v}{2} + i\left(2 - \frac{u}{2} + \frac{v}{2}\right)$$

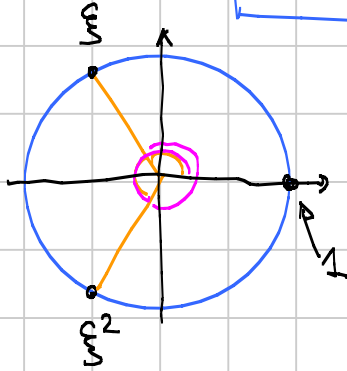
$$s - r = 2 + \frac{v}{2} - \frac{u}{2} - i\left(\frac{u+v}{2}\right)$$

$$i(s - r) = t \quad \text{finito}$$

Es 2.



Lemma: u, v, w formano un triangolo equilatero se
 $u + \xi v + \xi^2 w = 0$
 dove ξ è una delle radici terze dell'unità ($\xi \neq 1$)



$$x^n - 1 = 0$$

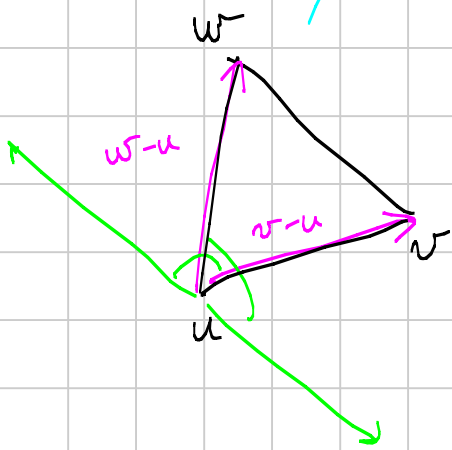
$$\xi = -\frac{1}{2} + i\frac{\sqrt{3}}{2}$$

$$(1 + \xi + \xi^2)(1 - \xi) = 0$$

$$1 + \xi + \xi^2 = 0$$

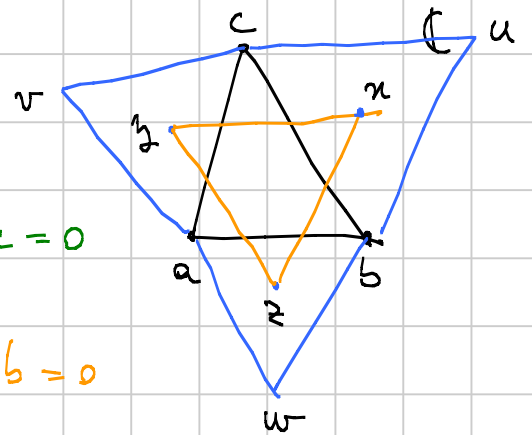
$$u + \xi v + \xi^2 w - u - \xi u - \xi^2 u = \xi(v - u) + \xi^2(w - u) = 0$$

↑
sse equil.



Occhio: se ξ è quello che ho scelto, u, v, w vanno presi in senso antiorario

torno all'esercizio



$$b + \xi u + \xi^2 c = 0 \quad \cdot \xi^2 \quad \xi^2 b + u + \xi c = 0$$

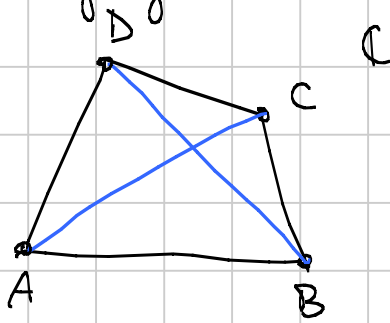
$$c + \xi v + \xi^2 a = 0$$

$$a + \xi w + \xi^2 b = 0 \quad \cdot \xi \quad \xi a + \xi^2 w + b = 0$$

$$x = \frac{b+u+c}{3} \quad \text{e analoghi}$$

$$3(x + \xi y + \xi^2 z) = \overset{\downarrow}{b} + \overset{\downarrow}{u} + \overset{\downarrow}{c} + \xi(\overset{\downarrow}{c} + \overset{\downarrow}{v} + \overset{\downarrow}{a}) + \xi^2(\overset{\downarrow}{a} + \overset{\downarrow}{w} + \overset{\downarrow}{b}) = 0$$

• Disuguaglianza di Tolomeo



$$AB \cdot CD + BC \cdot DA \geq AC \cdot BD$$

uguagliante

$\overline{AB} = |a-b|$ e analoghi

$$|a-b||c-d| + |b-c||d-a| - |a-c||b-d| \geq 0$$

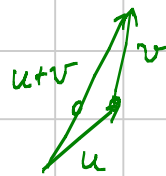
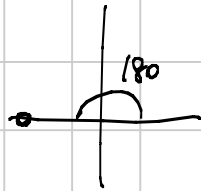
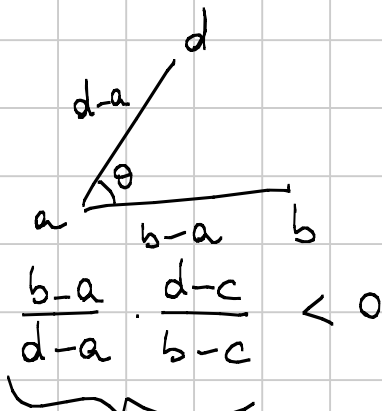
$$|ac - ad - bc + bd| + |bd - ba - cd + ac| - |ab - ad - bc + cd| \geq$$

$$\geq |ac - ad - bc + bd - bd + ba + cd - ac| - |ab - ad - bc + cd| = 0$$

vale = solo se

$$\frac{(a-b)(c-d)}{(b-c)(a-d)} > 0$$

reale e positivo



disuguaglianza triangolare

a, b, c

$$|a-b| \leq |a-c| + |c-b|$$

$u+v$ u v

$\forall u, v \in \mathbb{C}$

$$|u+v| \leq |u| + |v|$$

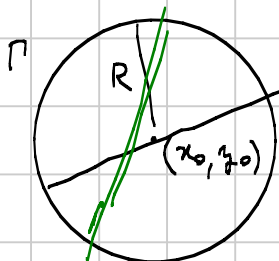
$\forall \vec{X}, \vec{Y}$

$$\|\vec{X} + \vec{Y}\| \leq \|\vec{X}\| + \|\vec{Y}\|$$

★ vale = se $u = \lambda v$ $\lambda > 0$

3 Torno alle cartesiane

• (Bisettrici), potenza, asse radicale .. alle fine, se riesco



$$Pow_P(P) = d^2 - R^2 = (x-x_0)^2 + (y-y_0)^2 - R^2$$

i punti della circonferenza sono quelli con $Pow_P(P) = 0$

$$\Pi_1, \Pi_2 \text{ due circonferenze } \left\{ P: \text{Pow}_{\Pi_1}(P) = \text{Pow}_{\Pi_2}(P) \right\} \quad P = (x, y)$$

$$(x-x_1)^2 + (y-y_1)^2 - R_1^2 = (x-x_2)^2 + (y-y_2)^2 - R_2^2$$

si ottiene lineare:

$$\underbrace{2(x_2-x_1)x}_a + \underbrace{2(y_2-y_1)y}_b + \underbrace{x_1^2 + y_1^2 - x_2^2 - y_2^2 - R_1^2 + R_2^2}_c = 0$$