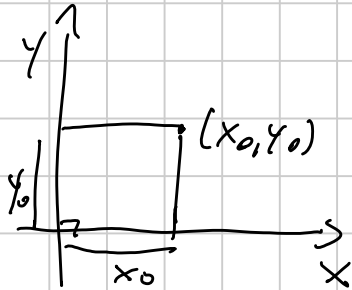
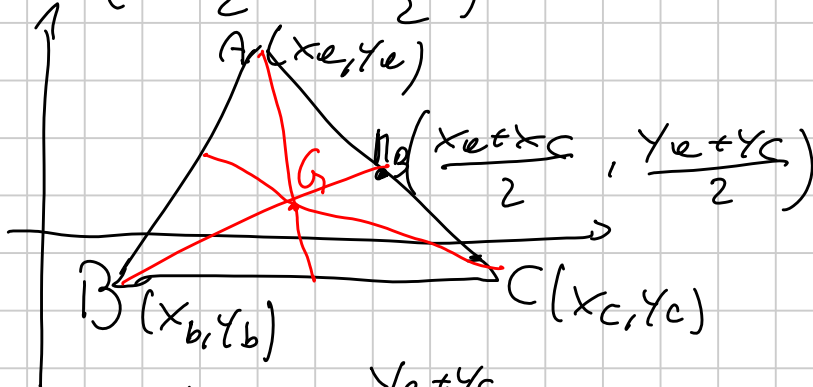


Cartesiano, Complessi e Vettori.

CARTESIANE



$A = (x_0, y_0)$ $B = (x_1, y_1)$ M il punto medio di AB
 $M = \left(\frac{x_0 + x_1}{2}, \frac{y_0 + y_1}{2} \right)$

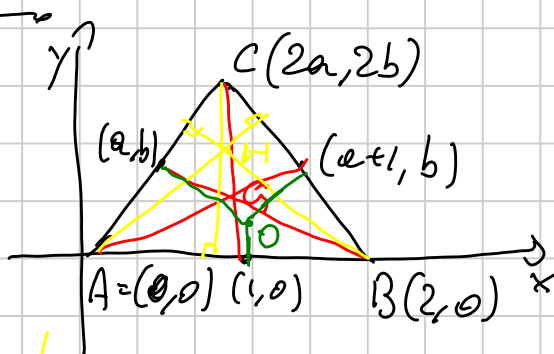


$$BG: \frac{y - y_b}{x - x_b} = \frac{\frac{y_a + y_c}{2} - y_b}{\frac{x_a + x_c}{2} - x_b}$$

$$AG: \frac{y - y_a}{x - x_a} = \frac{\frac{y_b + y_c}{2} - y_a}{\frac{x_b + x_c}{2} - x_a}$$

(generalizzazione: la retta per due punti è $\frac{y - y_0}{x - x_0} = \frac{y_1 - y_0}{x_1 - x_0}$)

$$G = \left(\frac{x_a + x_b + x_c}{3}, \frac{y_a + y_b + y_c}{3} \right)$$



$$G = \left(\frac{2}{3}(a+1), \frac{2}{3}b \right)$$

Calcoliamo H : $CH \perp AB$

$$x_H = x_C = 2a$$

$AH \perp BC$

$$m_{BC} \hat{=} \frac{y_b - y_c}{x_b - x_c} = \frac{-2b}{2 - 2a} = \frac{b}{a-1}$$

$$m_{AH} = \frac{1-a}{b}$$

$$AH: y = \frac{1-a}{b}x$$

$$H = \left(2a, \frac{2a-2a^2}{b} \right)$$

Calcoliamo O :

$$\begin{aligned} \text{sta sull'asse di } AB &\Rightarrow x_0 = 1 \\ \text{sta sull'asse di } AC & y = -\frac{a}{b}x + \frac{a^2}{b} + b \end{aligned}$$

$$O = \left(1, -\frac{a}{b} + \frac{a^2}{b} + b \right)$$

$$\frac{x_H - x_G}{y_H - y_G} \stackrel{?}{=} \frac{x_O - x_G}{y_O - y_G}$$

$$\frac{2a - \frac{2}{3}(a+1)}{\frac{2a-2a^2}{b} - \frac{2}{3}b} \stackrel{?}{=} \frac{1 - \frac{2}{3}(a+1)}{-\frac{a}{b} + \frac{a^2}{b} + b - \frac{2}{3}b}$$

$$\frac{b(6a - 2(a+1))}{6a - 6a^2 - 2b^2} \stackrel{?}{=} \frac{b(3 - 2(a+1))}{-3a + 3a^2 + b^2 - 2b^2}$$

$$\frac{4a - 2}{6a - 6a^2 - 2b^2} \stackrel{?}{=} \frac{1 - 2a}{-3a + 3a^2 + b^2}$$

$$\frac{2a - 1}{3a - 3a^2 - b^2} \stackrel{?}{=} \frac{1 - 2a}{-3a + 3a^2 + b^2} \quad \text{vero!}$$

H, G, O allineati.

C'è di più:

$$\begin{aligned} y_H - y_G &= -2(y_O - y_G) \\ x_H - x_G &= -2(x_O - x_G) \Rightarrow HG = 2GO \end{aligned}$$

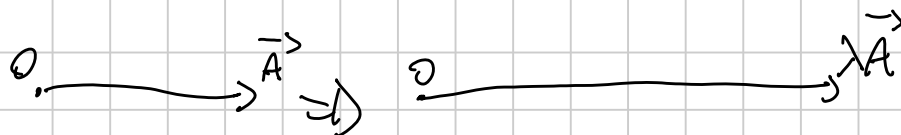
Vettori:



Somma:



Moltiplicazione per scalare:

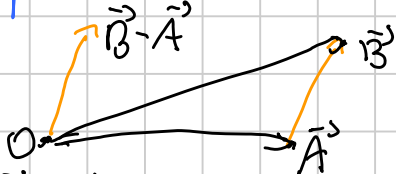


$\lambda = 0$
 $\lambda = 1$ resto \vec{A}
 $\lambda = -1$ $-\vec{A}$

- scelta del vettore \vec{A}

$$\vec{B} = \lambda \vec{A}$$

- scelta per 2 due vettori, \vec{A}, \vec{B}

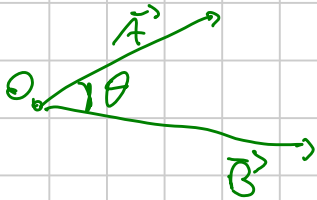


$$z: \lambda(\vec{B} - \vec{A}) + \vec{A}$$

$$z: \lambda \vec{B} + (1 - \lambda) \vec{A}$$

SEGMENTO si ha $0 \leq \lambda \leq 1$

PRODOTTO SCALARE:



$$\vec{A} \cdot \vec{B} = \|\vec{A}\| \cdot \|\vec{B}\| \cdot \cos \theta$$

"quanto è lungo \vec{A} "

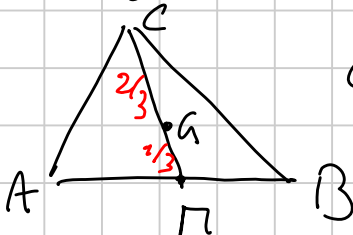
OSS: $\vec{A} \cdot \vec{A} = \|\vec{A}\|^2$

$$\vec{A} \cdot (-\vec{A}) = -\|\vec{A}\|^2$$

CALCOLIAMO UN PO' DI PT NOTI:

dati \vec{A} e \vec{B} il punto medio \vec{M} e

$$\vec{M} = \frac{1}{2} \vec{B} + (1 - \frac{1}{2}) \vec{A} = \frac{1}{2} \vec{A} + \frac{1}{2} \vec{B}$$

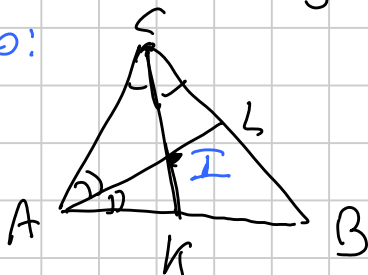


$$CG = 2GM$$

$$\frac{CG}{CM} = \frac{2}{3}$$

$$\vec{G} = \lambda \vec{C} + (1 - \lambda) \vec{M} = \frac{1}{3} \vec{C} + \frac{2}{3} \vec{M} = \frac{\vec{A} + \vec{B} + \vec{C}}{3}$$

Incentro:



$$\frac{AK}{KB} = \frac{AC}{BC} = \frac{b}{a}$$

$$\frac{AK}{AB} = \frac{b}{a+b}$$

$$AK = \frac{bc}{a+b}$$

$$\vec{K} = \frac{b}{a+b} \vec{B} + \frac{a}{a+b} \vec{A}$$

$$\frac{CI}{IK} = \frac{AC}{AK} = \frac{b}{\frac{bc}{a+b}} = \frac{a+b}{c}$$

$$\frac{CI}{CK} = \frac{CI}{CI+IK} = \frac{1}{\frac{CI+IK}{CI}} = \frac{1}{1+\frac{IK}{CI}} = \frac{1}{1+\frac{c}{a+b}} = \frac{a+b}{a+b+c}$$

$$\vec{I} = \frac{a+b}{a+b+c} \vec{K} + \frac{c}{a+b+c} \vec{C} = \frac{a\vec{A}+b\vec{B}+c\vec{C}}{a+b+c}$$

Ortocentro:



$$\vec{H} - \vec{G} = 2(\vec{G} - \vec{O})$$

$$\vec{H} = 3\vec{G} - 2\vec{O} = \vec{A} + \vec{B} + \vec{C} - 2\vec{O}$$

È molto molto comodo prendere come origine del sistema vettoriale il circocentro O .

In questo caso si ha

$$\vec{H} = \vec{A} + \vec{B} + \vec{C}$$

Oss: \vec{A} e \vec{B} sono \perp $\Leftrightarrow \vec{A} \cdot \vec{B} = 0$

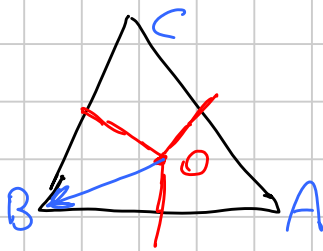
È vero che $\vec{H} = \vec{A} + \vec{B} + \vec{C}$?

$$(\vec{H} - \vec{C}) \cdot (\vec{B} - \vec{A}) \stackrel{?}{=} 0$$

$$(\vec{B} + \vec{A}) \cdot (\vec{B} - \vec{A}) \stackrel{?}{=} 0$$

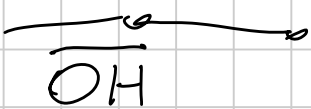
$$\vec{B} \cdot (\vec{B} - \vec{A}) + \vec{A} \cdot (\vec{B} - \vec{A}) = \vec{B} \cdot \vec{B} - \vec{B} \cdot \vec{A} + \vec{A} \cdot \vec{B} - \vec{A} \cdot \vec{A} \stackrel{?}{=} 0$$

$$\vec{B} \cdot \vec{B} = \|\vec{B}\|^2$$

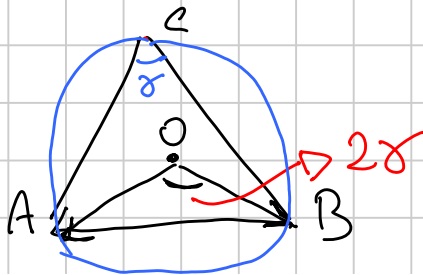


$$\vec{B} \cdot \vec{B} = R^2 = \vec{A} \cdot \vec{A}$$

Quindi è proprio O .



$$\begin{aligned} OH^2 &= \|\vec{OH}\|^2 = \vec{OH} \cdot \vec{OH} = (\vec{A} + \vec{B} + \vec{C}) \cdot (\vec{A} + \vec{B} + \vec{C}) = \\ &= \vec{A} \cdot \vec{A} + \vec{B} \cdot \vec{B} + \vec{C} \cdot \vec{C} + 2\vec{A} \cdot \vec{B} + 2\vec{A} \cdot \vec{C} + 2\vec{B} \cdot \vec{C} \end{aligned}$$



$$\begin{aligned} \vec{A} \cdot \vec{B} &= R^2 \cos 2\alpha = R^2 - \frac{4R^2 \sin^2 \alpha}{2} \\ \cos 2\alpha &= 1 - 2\sin^2 \alpha \end{aligned}$$

$$\vec{A} \cdot \vec{B} = R^2 - \frac{1}{2} [(2R \sin \alpha)^2] = R^2 - \frac{c^2}{2}$$

$$\vec{A} \cdot \vec{C} = R^2 - \frac{b^2}{2} \quad \vec{B} \cdot \vec{C} = R^2 - \frac{a^2}{2}$$

$$OH^2 = 3R^2 + 2(R^2 - \frac{c^2}{2}) + 2(R^2 - \frac{b^2}{2}) + 2(R^2 - \frac{a^2}{2})$$

$$OH^2 = 9R^2 - (a^2 + b^2 + c^2)$$

CALCOLIAMO OI

$$OI^2 = \|\vec{OI}\|^2 = \vec{OI} \cdot \vec{OI} = \left(\frac{a\vec{A} + b\vec{B} + c\vec{C}}{a+b+c} \right) \cdot \left(\frac{a\vec{A} + b\vec{B} + c\vec{C}}{a+b+c} \right) =$$

$$= \frac{1}{(a+b+c)^2} \left[(a^2 + b^2 + c^2)R^2 + 2(ab\vec{A} \cdot \vec{B} + ac\vec{A} \cdot \vec{C} + bc\vec{B} \cdot \vec{C}) \right] =$$

$$= \frac{1}{(a+b+c)^2} \left[R^2(a^2 + b^2 + c^2) + 2R^2(ab + ac + bc) + abc(a+b+c) \right] =$$

$$= \frac{1}{(a+b+c)^2} \left[R^2(a+b+c)^2 - abc(a+b+c) \right] = R^2 - \frac{abc}{a+b+c}$$

$$R = \frac{abc}{4S} \quad z = \frac{2S}{a+b+c} \Rightarrow R z = \frac{abc}{a+b+c}$$

$$OI^2 = R^2 - 2Rz$$

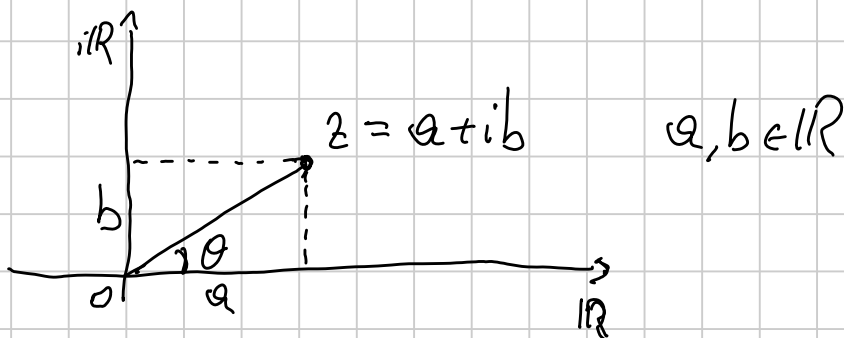
Abbiamo $R^2 - 2Rz \geq 0$

$$\boxed{R \geq 2z}$$

CALCOLATE GH .

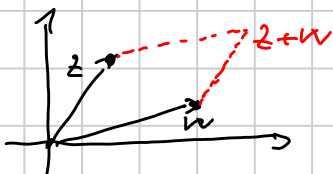
$$GH^2 = 4R^2 - \frac{4}{9}(a^2 + b^2 + c^2)$$

COMPLESSI



$$z = a + ib = |z|(\cos \theta + i \sin \theta) = |z| e^{i\theta} = (\sqrt{a^2 + b^2}) e^{i\theta}$$

$$z = a + ib \quad w = c + id \quad z + w = (a+c) + i(b+d)$$



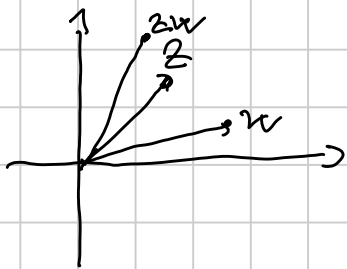
$$zw = ac + (ad+bc)i + i^2 bd$$

$$i^2 = -1$$

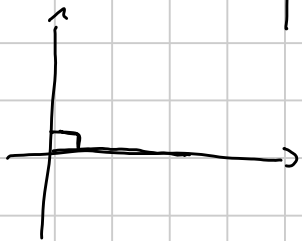
$$zw = (ac - bd) + i(ad+bc)$$

$$z = |z| e^{i\theta} \quad w = |w| e^{i\varphi}$$

$$zw = |z| \cdot |w| \cdot e^{i\theta+i\varphi} = |z| \cdot |w| \cdot e^{i(\theta+\varphi)}$$

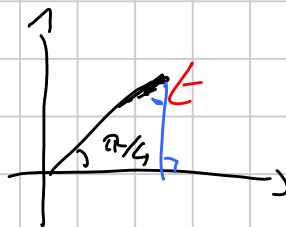
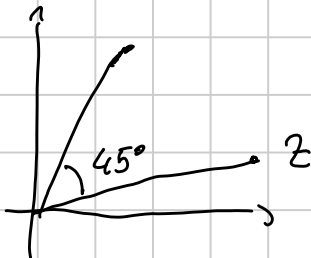


$$|zw| = |z| \cdot |w|$$



$$i = e^{i\theta} = e^{i\pi/2}$$

$$-1 = e^{i\pi}$$



$$e = a + ib$$

$$|e| = 1 \Rightarrow a^2 + b^2 = 1$$

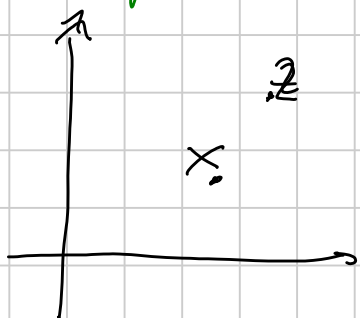
$$a = b \geq 0$$

$$a = b = \frac{\sqrt{2}}{2}$$

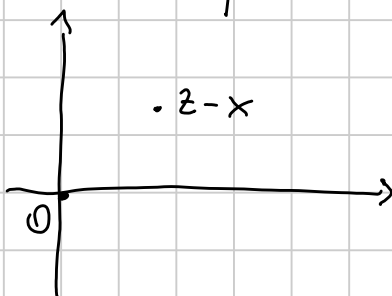
$$e = \frac{\sqrt{2}}{2}(1+i)$$

Quindi per ruotare z di 45° intorno all'origine dobbiamo moltiplicarlo per $\frac{\sqrt{2}}{2}(1+i) = e^{i\pi/4}$.

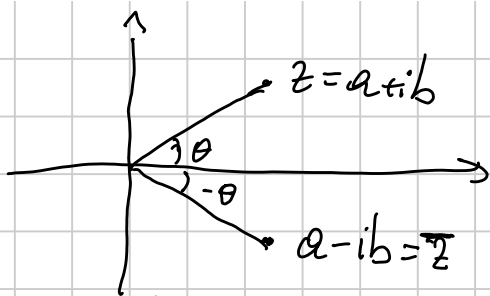
Dato x complesso come ruoto intorno ad x ?



fissiamo θ



$$z' = (z-x)e^{i\theta} + x$$

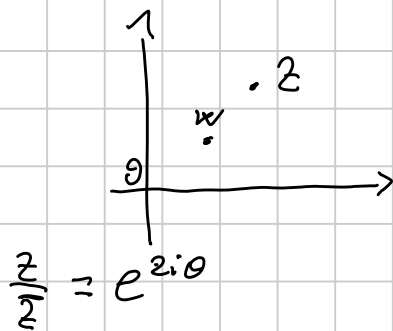


\bar{z} si dice coniugato di z .

$$z\bar{z} = (a+ib)(a-ib) = a^2 - (ib)^2 = a^2 - i^2b^2 = a^2 + b^2 = |z|^2 = |\bar{z}|^2$$

$$z = |z|e^{i\theta} \quad \bar{z} = |z|e^{-i\theta}$$

Cosa vuol dire $z, w, 0$ allineati?



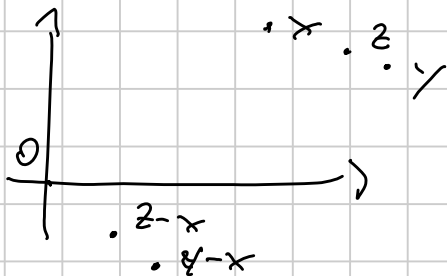
$$z = |z|e^{i\theta} \quad w = |w|e^{i\varphi}$$

$$\frac{z}{|z|} = e^{2i\theta}$$

$$e^{2i(\pi+\theta)} = \underbrace{e^{2i\pi}}_1 e^{2i\theta} = e^{2i\theta}$$

Sono allineati se e solo se $\frac{z}{\bar{z}} = \frac{w}{\bar{w}}$

Cosa vuol dire x, y, z allineati?



x, z, y allineati

$0, z-x, y-x$ allineati

$$\frac{z-x}{z-x} = \frac{y-x}{y-x}$$

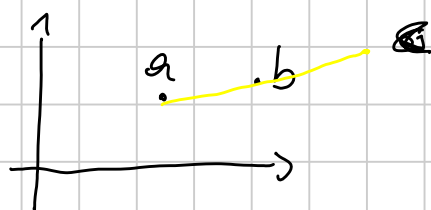
OSS: $\frac{\overline{w+t}}{\overline{wt}} = \frac{\bar{w} + \bar{t}}{\bar{w}\bar{t}}$

$$\frac{z-x}{\bar{z}-\bar{x}} = \frac{y-x}{\bar{y}-\bar{x}}$$

Come si trova il punto medio tra a e b ?

$$m = \frac{a+b}{2}$$

Se vogliamo riflettere un punto risp ad un altro, ed esempio a risp b



$$\frac{a+c}{2} = b \quad c = 2b - a$$

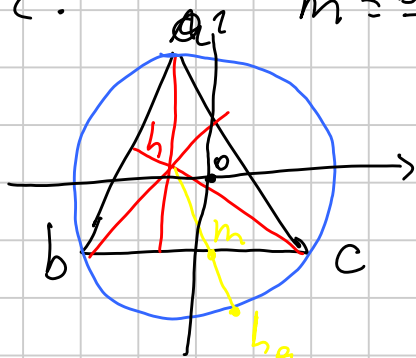
Vogliamo riflettere $1+i$ rispetto a $3+7i$

$$c = 2b - a = 6 + 14i - 1 - i = 5 + 13i$$

Vogliamo dimostrare che il simmetrico dell'ortocentro H rispetto al punto medio di BC è sulla circonscritta ed è il diametralmente opposto ad A .

Sol Prendiamo come circonscritta la circonferenza unitaria. Allora $a\bar{a}=1$ $b\bar{b}=1$ $c\bar{c}=1$, $o=0$ e $h = a+b+c$.

$$h_a = 2m - h$$



$$h_a = b + c - a - b - c$$

$$h_a = -a$$

$$(-a)(-\bar{a}) = (-a)(\bar{a}) = a\bar{a} = 1$$

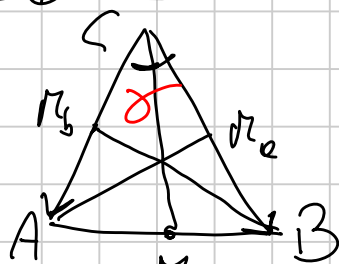
Inoltre $a + (-a) = 0$ quindi $-a$ è il diametralmente opposto ad a .

ES: PI: 12, 22, 24

PII: 6, 10, 16

PIII: 2014 B1

P6



$$CM_c^2 + BM_c^2 + AM_c^2$$

$$\vec{m}_c = \frac{\vec{A} + \vec{B}}{2}$$

$$CM_c^2 = \vec{CM}_c \cdot \vec{CM}_c = (\vec{m}_c - \vec{C})(\vec{m}_c - \vec{C}) = \left(\frac{\vec{A} + \vec{B}}{2} - \vec{C}\right) \left(\frac{\vec{A} + \vec{B}}{2} - \vec{C}\right)$$

Origine vettoriale in \vec{C} .

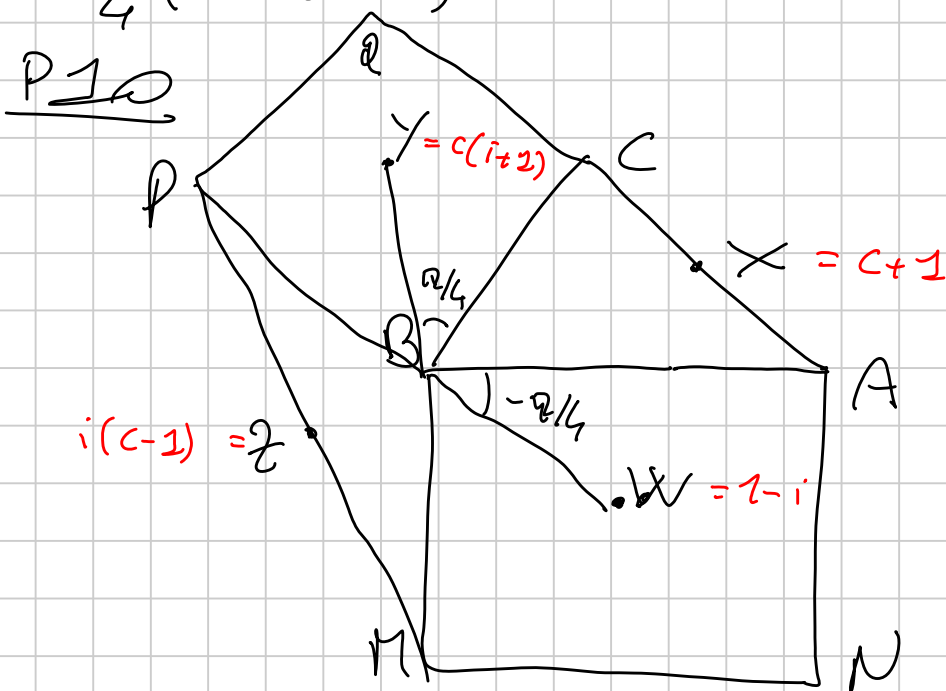
$$CM_c^2 = \frac{1}{4} (\vec{A} + \vec{B})(\vec{A} + \vec{B}) = \frac{1}{4} \vec{A} \cdot \vec{A} + \frac{1}{4} \vec{B} \cdot \vec{B} + \frac{1}{2} \vec{A} \cdot \vec{B} = \frac{1}{4} a^2 + \frac{1}{4} b^2 + \frac{1}{2} \vec{A} \cdot \vec{B}$$

$$CM_c^2 = \frac{1}{4} a^2 + \frac{1}{4} b^2 + \frac{3}{4} ab \cos \gamma$$

$$c^2 = a^2 + b^2 - 2ab \cos \delta \quad 2ab \cos \delta = a^2 + b^2 - c^2$$

$$CM_c^2 = \frac{1}{4} (2a^2 + 2b^2 - c^2)$$

$$CM_c^2 + AM_A^2 + BM_B^2 = \frac{1}{4} (2a^2 + 2b^2 - c^2 + 2b^2 + 2c^2 - a^2 + 2a^2 + 2c^2 - b^2) = \frac{3}{4} (a^2 + b^2 + c^2)$$



$$B = 0 \quad A = 2 \quad C = 2c$$

$$x = c+1$$

$$BW = \frac{\sqrt{2}}{2} BA$$

$$w = 2 \cdot \frac{\sqrt{2}}{2} \cdot \left(\frac{\sqrt{2}}{2} (1-i) \right) = 1-i$$

$$y = 2c \cdot \frac{\sqrt{2}}{2} \left(\frac{\sqrt{2}}{2} (1+i) \right) = c(1+i)$$

$$m = 2(-i) = -2i$$

$$p = 2ci = 2ic$$

$$z = i(c-1)$$

$$w \stackrel{?}{=} i(y-x) + x$$

$$1-i \stackrel{?}{=} i(c+ci - c-1) + c+1$$

$$1-i \stackrel{?}{=} i\cancel{c} - \cancel{c} - i\cancel{c} - i + \cancel{c} + 1$$

$$w \stackrel{?}{=} -i(y-z) + z$$

$$1-i \stackrel{?}{=} -i(c+ci - ci+i) + ci-i$$

$$1-i \stackrel{?}{=} -\cancel{c}i + \cancel{c} - \cancel{c} + 1 + \cancel{c}i - i$$

Allora YXW e YZW sono isosceli e rettangoli
 su base $YW \Rightarrow XYZW$ è quadrato.

$$P16 \quad \vec{M} = \frac{\vec{A} + \vec{B}}{2} \quad \vec{N} = \frac{\vec{B} + \vec{C}}{2} \quad \vec{O} = \frac{\vec{C} + \vec{D}}{2} \quad \vec{P} = \frac{\vec{A} + \vec{D}}{2}$$

$$MO = NP \Leftrightarrow \|\vec{MO}\| = \|\vec{NP}\| \Leftrightarrow \|\vec{C} + \vec{D} - \vec{A} - \vec{B}\| = \|\vec{A} + \vec{D} - \vec{B} - \vec{C}\|$$

$$\vec{x} = \vec{C} - \vec{A} \quad \vec{y} = \vec{D} - \vec{B}$$

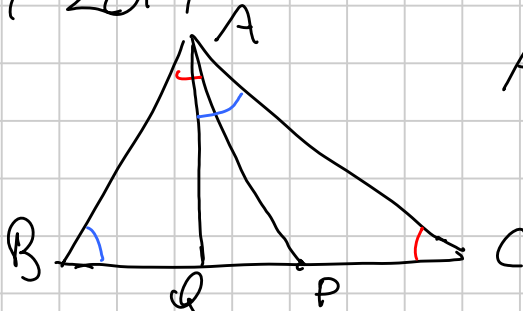
$$\|\vec{y} + \vec{x}\| = \|\vec{y} - \vec{x}\|$$

$$\Leftrightarrow (\vec{y} + \vec{x})(\vec{y} + \vec{x}) = (\vec{y} - \vec{x})(\vec{y} - \vec{x}) \Leftrightarrow 4\vec{x} \cdot \vec{y} = 0 \Leftrightarrow \vec{x} \cdot \vec{y} = 0$$

$$\vec{x} = \vec{C} - \vec{A} = \vec{AC} \quad \vec{y} = \vec{D} - \vec{B} = \vec{BD}$$

$$AC \perp BD \Leftrightarrow \vec{AC} \cdot \vec{BD} = 0$$

IMO 4 2014



$$ABP \sim CBA$$

$$\frac{BP}{AB} = \frac{BA}{CB} \quad BP = \frac{c^2}{a}$$

$$\frac{BP}{BC} = \frac{c^2}{a^2}$$

$$\vec{P} = \frac{c^2}{a^2} \vec{C} + \frac{a^2 - c^2}{a^2} \vec{B}$$

$$ACQ \sim BCA$$

$$\vec{Q} = \frac{b^2}{a^2} \vec{B} + \frac{a^2 - b^2}{a^2} \vec{C}$$

$$\frac{CQ}{AC} = \frac{CA}{BC} \quad CQ = \frac{b^2}{a}$$

$$\vec{M} = 2\vec{P} - \vec{A} = \frac{2c^2}{a^2} \vec{C} + \frac{2a^2 - 2c^2}{a^2} \vec{B} - \vec{A}$$

$$\vec{N} = \frac{2b^2}{a^2} \vec{B} + \frac{2a^2 - 2b^2}{a^2} \vec{C} - \vec{A}$$

$$BM: \lambda \left(\frac{2c^2}{a^2} \vec{C} + \frac{2a^2 - 2c^2}{a^2} \vec{B} - \vec{A} \right) + (1 - \lambda) \vec{B}$$

$$CN: \mu \left(\frac{2b^2}{a^2} \vec{B} + \frac{2a^2 - 2b^2}{a^2} \vec{C} - \vec{A} \right) + (1 - \mu) \vec{C}$$

$$\vec{X} = \frac{1}{2b^2 + 2c^2 - a^2} \left(-a^2 \vec{A} + 2b^2 \vec{B} + 2c^2 \vec{C} \right)$$

$$\lambda = \frac{a^2}{2b^2 + 2c^2 - a^2} = \mu$$

Resta de verificare $\vec{X} \cdot \vec{X} \stackrel{?}{=} R^2$ (origine in O)

$$R^2 (2b^2 + 2c^2 - a^2)^2 \stackrel{?}{=} (-a^2 \vec{A} + 2b^2 \vec{B} + 2c^2 \vec{C}) \cdot (-a^2 \vec{A} + 2b^2 \vec{B} + 2c^2 \vec{C})$$

$$RHS = (a^4 + 4b^4 + 4c^4)R^2 - 4a^2b^2 \underbrace{\left(R^2 - \frac{c^2}{2}\right)}_{\vec{A} \cdot \vec{B}} - 4a^2c^2 \underbrace{\left(R^2 - \frac{b^2}{2}\right)}_{\vec{A} \cdot \vec{C}} + 8b^2c^2 \underbrace{\left(R^2 - \frac{a^2}{2}\right)}_{\vec{B} \cdot \vec{C}}$$

$$RHS = R^2(2b^2 + 2c^2 - a^2)^2 + 2a^2b^2c^2 + 2a^2b^2c^2 - 4a^2b^2c^2 = LHS$$

Abbiamo dimostrato che ABC è ciclico.